## Thermal Stability Anal ysis for a Heliocentric Gravitational Radiation Detection Mission

W. M. Folkner, P. McElroy, R. Miyake Jet Propulsion Laboratory, Pasadena, CA

P.L. Bender and R. T. Stebbins
Joint Institute for Laboratory Astrophysics, Boulder, CO

W. Supper European Space Research and Technolog y Center, Noord wijk, the Netherlands

The Laser infer-cromcfer Space A ntenna (1.1SA) mission is designed for detailed studies of lozu-frequency gravitational radiation. The mission is currently a candidate for ESA's post-llorizon 2000 program. Thermal noise affects the measurement in at least two ways, Thermal variation of the length of the optical cavity to which the lasers are stabilized in troduces phase variations in f he interferometer sign al, which have to be correct ed for by using dat a from the two arms separately. Variations in the dimensions of the spacecraft structure will change the gravitational field experienced by the test masses and the length of the tran smif/receive telescope. We have constructed a model of an early version of the LISA spacecraft in order to estimate f he thermal variations.

The LISA mission concept currently consists of four spacecraft in 1 AU orbits about the sun -2,0 degrees behind the Earth. A test mass inside each spacecraft is shielded from external non-gravitational influences. The separation between test masses is measured using laser interferometers. The LISA mission goal is to measure gravitational radiation in the range from  $10^4$ Hz to  $10^{-2}$ Hz with greatest sensitivity of  $10^{21}/\sqrt{\text{Hz}}$  between  $10^3$  and  $10^{-2}$ Hz. With twice the arm length being  $10^{10}$  m this means the relative displacement of the proof masses must be measured with an accuracy of  $10\text{pm}/\sqrt{\text{Hz}}$ . Two spacecraft are close together (about 200 km apart) and form the vertex of the "V" formation. The two end spacecraft define the size of the array, The individual orbits are chosen to maintain the formation as exactly as possible.

The master laser cm one of the central spacecraft is locked to a reference cavity. A change of length of the cavity due to temperature change produces a laser frequency shift and a corresponding error in the displacement measurement of the test mass. The laser phase noise can be canceled between the arms using a Fourier-transform processing technique by an amount  $4\pi f \sigma_l / c$  where  $\sigma_l$  is the uncertainty in knowledge of the arm lengths and f is the observation frequency. The thermal noise sets the level of arm length determination needed and also the precision needed in the phase measurement to allow the necessary level of phase noise cancellation.

A cross-section of the payload module within each spacecraft is shown in Fig. 1, The payload module includes a structural graphite-epoxy cylinder within which are the test mass, telescope, and position measurement laser and electronics. The laser is mounted on a radiator disk at the one end of the graphite-epoxy cylinder. Capacitive sensors are used to measure the position of the test mass within a central optical bench which is rigidly attached to the spacecraft. The displacement measurements are used to center the spacecraft about the test mass. Electronics for the capacitive sensors and amplifiers for the laser photo-diodes are mounted on a disk between the optical bench and the laser radiator. A cylindrical thermal shield surrounds the payload structural cylinder to provide isolation from the rest of the spacecraft. The external spacecraft is shown in Fig. 2. It consists of a central structural cylinder within which the payload is suspended, and a trapezoidal box which contains the attitude control thrusters and electronics, the telemetry system, star trackers, and other elements. Solar panels located on the sun-facing side of the box provide spacecraft power. The normal to the "top" of the box always points 30° from the sun.

A thermal model for the entire spacecraft was formed with single nodes for the box panels, solar panels, optical bench, telescope, laser radiator and electronics disk. The largest thermal load is from incident sunlight. Electrical power dissipation occurs on the outer spacecraft panels; the laser radiator, the payload electronics disk. A small amount of power is needed on the optical bench to bias the photodetectors and drive a phase-modulator. Observed solar insolation variations from 10<sup>4</sup>Hz to 10-2

can be described by a power spectral density of AL =  $1.3x \cdot 10^{-4} f^{-1/3} L_0 W/m^2/\sqrt{H} z$  with L =  $1350 W/m^2$ . The power fluctuations of electrical components will be actively controlled to keep them from inducing temperature variations greater than those caused by solar variation.

The transfer functions giving the temperature response for unit variation in power dissipation for the optical bench (which contains the laser reference cavity) arc given in Table 1. As an example of reading Table 1, the variation of solar insolation of  $1.8 \, \text{W/m}^2/\sqrt{\text{Hz}}$  at  $10^3 \, \text{Hz}$  is multiplied by  $3.7 \times 10^{-9}$  to find the optical bench temperature noise of  $6.7 \, \text{nK/VHz}$ . To keep the electronic power variations from producing thermal noise in excess of this, the power dissipation of the payload electronics will have to be controlled to  $10^{-4} \, \text{W/VHz}$  and the photo-diode power will have to be controlled to  $0.3 \, \mu \text{W/VHz}$ . The photodiodes (and phase modulator) arc assumed to draw  $0.4 \, \text{W}$  at  $40 \, \text{V}$ . A 200 Ohm resistor (small compared to the load resistance of 4000 Ohm) is placed in series with the load. The voltage across the load and across the 200 Ohm resistor arc measured with an op-amp with voltage noise at  $1 \, \text{mHz}$  of  $1 \, \mu \text{V/VHz}$ . The voltage and power measurement arc multiplied to give the power dissipation and included in a feedback loop that maintains constant power. The power noise at  $1 \, \text{mHz}$  is then  $1 \, \mu \text{V/VHz} \times 0.01 \, \text{A} + 5 \, \text{nA/VHz} \times 40 \, \text{V} = 0.2 \, \mu \text{W/VHz}$ .

The primary payload masses, aside from the optical bench, are the? telescope, the payload electronics, and the laser/radiator combination with masses 13.97 kg, 3.53 kg, and 14.85 kg. The distances to the test mass arc -0,355 m, 0.250 m, and 0.522 m. The nominal acceleration of the test mass due to the other payload masses is  $2 \times 10^{-12} \text{m/s}^2$  and the acceleration gradient is  $8.6 \times 10^{8}/\text{s}^2$ . The three masses move with respect to the test mass due to thermal expansion of the payload cylinder from which they are suspended, which has coefficient of thermal expansion 0.4x10 $^{6}/\text{K}$ . Table 2 gives the position noise from thermally-induced gravitational changes driven by solar variations.

Table 1. Temperature response of optical bench for uni t

Table 2. Thermallydriven gravity change\_

f(Hz)         solar variation variation variation         spacecraft electronics electronics         payload electronics         Laser blood diodes         Photo- diodes         f(Hz)         motion noise (m√Hz)           1.0E-06         5.9E-01         3.1E-01         3.3E+00         3.7E-01         8.7E+00         1.0E-06         2.8E-05           1.0E-05         1.6E-03         1.3E-03         1.9E-01         3.1E-03         1.2E+00         1.0E-05         2.2E-08           1.0E-04         3.5E-06         4.6E-07         2.1E-03         5.4E-06         1.2E-01         1.0E-04         8.2E-12           1.0E-03         3.7E-09         3.2E-11         2.1 E-05         5.4E-09         1.2E-02         1.0E-03         2.4E-16           1.0E-02         3.7E-12         3.0E-15         2.1E-07         5.4E-12         1.2E-03         1.0E-02         7.6E-21	change in power dissipation.						univen gravity change_	
K/(W/m²)         K / W         K/W         K/W         K/W         K/W         K/W         K/W         K/W         K/W         (m/Hz)           1.0E-06         5.9E-01         3.1E-01         3.3E+00         3.7E-01         8.7E+00         1.0E-06         2.8E-05           1.0E-05         1.6E-03         1.3E-03         1.9E-01         3.1E-03         1.2E+00         1.0E-05         2.2E-08           1.0E-04         3.5E-06         4.6E-07         2.1E-03         5.4E-06         1.2E-01         1.0E-04         8.2E-12           1.0E-03         3.7E-09         3.2E-11         2.1 E-05         5.4E-09         1.2E-02         1.0E-03         2.4E-16	f(Hz)			1 2	Laser		f(Hz)	
1.0E-06     5.9E-01     3.1E-01     3.3E+00     3.7E-01     8.7E+00     1.0E-06     2.8E-05       1.0E-05     1.6E-03     1.3E-03     1.9E-01     3.1E-03     1.2E+00     1.0E-05     2.2E-08       1.0E-04     3.5E-06     4.6E-07     2.1E-03     5.4E-06     1.2E-01     1.0E-04     8.2E-12       1.0E-03     3.7E-09     3.2E-11     2.1 E-05     5.4E-09     1.2E-02     1.0E-03     2.4E-16			electronics	electronics		diodes		
1.0E-05       1.6E-03       1.3E-03       1.9E-01       3.1E-03       1.2E+00       1.0E-05       2.2E-08         1.0E-04       3.5E-06       4.6E-07       2.1E-03       5.4E-06       1.2E-01       1.0E-04       8.2E-12         1.0E-03       3.7E-09       3.2E-11       2.1 E-05       5.4E-09       1.2E-02       1.0E-03       2.4E-16		K/(W/m <sup>2</sup> )	<b>K</b> / <b>W</b>	K/W	K/W	K/W		(m/√Hz)
1.OE-04       3.5E-06       4.6E-07       2.1E-03       5.4E-06       1.2E-01       1.0E-04       8.2E-12         1.0E-03       3.7E-09       3.2E-11       2.1 E-05       5.4E-09       1.2E-02       1.0E-03       2.4E-16	1.0E-06	5.9E-01	<b>3.1</b> E-01	3.3E+00	3.7E-01	8.7E+00	1.0E-06	2.8E-05
<b>1.0E-03 3.7E-09</b> 3.2E-11 2.1 E-05 <b>5.4E-09 1.2E-02 1.0E-03 2.4E-16</b>	1.0E-05	1.6E-03	1.3E-03	1.9E-01	3.1E-03	1.2E+00	1.0E-05	2.2E-08
	1.OE-04	3.5E-06	4.6E-07	<b>2.1</b> E-03	5.4E-06	1.2E-01	1.0E-04	8.2E-12
1.0E-02 3.7E-12 3.0E-15 2.1E-07 5.4E-12 1.2E-03 1.0E-02 7.6E-21	1.0E-03	3.7E-09	3.2E-11	2.1 E-05	5.4E-09	1.2E-02	1.0E-03	2.4E-16
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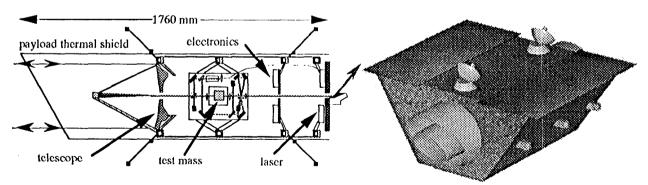


Figure 1, LISA payload schematic

Figure 2. LISA spacecraft

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